Create "listeners" for the three events: Red and Blue are touch sensor listeners. Yellow is a light threshold listener. Then activate the three listeners.

An infinite loop (between green jump/land describing default behavior to execute while listening for events.

Go forward at power level 4 for up to 3 seconds, then slow down motor C to power level 2 (effectively turning towards C) for up to 8 seconds.

"Forked" behaviors to execute when events are detected.

Forks must be recombined in the order they were split.